

Review

Lecture 9

1.1 Linear equations

- What is a linear equation
- Matrix notation
- What is a solution or solution set.
- Key: row-equivalence: elementary row operations do not change the solution
- Consistent \Rightarrow has one or more solutions

1.2 Row-reduction

- ↳ The workhorse algo
- ↳ row-echelon form often enough to see if the system has a solution
- ↳ reduced row-echelon form is unique.
(Every matrix has only one reduced row echelon form)

1.3 Vector equations

- ↳ Vector = matrix with one column.
- ↳ Know how to handle them
- ↳ linear combination
- ↳ Span $\{v_1 \dots v_p\}$

1.4 Matrix Eq $\underline{\underline{A}}x = \underline{b}$

- ↳ $\underline{\underline{A}}x = x_1 \underline{a}_1 + x_2 \underline{a}_2 + \dots + x_n \underline{a}_n$
or "row \times column"
- ↳ When is $\underline{\underline{A}}x = \underline{b}$ consistent for all \underline{b} ?
- ↳ How to solve $\underline{\underline{A}}x = \underline{b}$?
- ↳ Vector eqn = $\underline{\underline{A}}x = \underline{b}$ = augmented matrix of linear sys

Homogeneous & Inhomogeneous eqns

- ↳ $\underline{A}\underline{x} = \underline{0}$ $\hat{=}$ homogeneous problem
 - has solutions only if there is a free variable
 - always has trivial solution
 - solution define planes through origin
- ↳ $\underline{A}\underline{x} = \underline{b}$ $\hat{=}$ inhomogeneous problem.
 - Any solution can be written as $\underline{x} = \underline{p} + \underline{x}_h$
 - Solutions are shifted planes

1.7

Linear independence

- ↳ $\{\underline{v}_1, \dots, \underline{v}_p\}$ lin. indep. $= x_1\underline{v}_1 + \dots + x_p\underline{v}_p = \underline{0}$
has only trivial solution

- ↳ $\{\underline{v}_1, \dots, \underline{v}_p\}$ are dependent

- ↳ one vector is a lin. combination of the others
- ↳ one vector is 0.

- ↳ if there are more vectors than elements in each vector, then they are lin. dependent.

1.8

1.9

Linear transformations

- ↳ Think of matrices as fctns! $T(\underline{x}) = \underline{A}\underline{x}$

- ↳ $\underline{A}\underline{x}$ is a linear fctn

- ↳ Range, domain etc are connected to $\underline{A}\underline{x} = \underline{b}$ solutions.

- ↳ every linear fctn $\hat{=} \underline{A}\underline{x} = \underline{b}$

the three planes ✓

$$x_1 + 2x_2 + x_3 = 4$$

$$x_2 - x_3 = 1$$

$$x_1 + 3x_2 + \quad = 0$$

at least
have one common point of intersection?

Solve system!

$$\left(\begin{array}{ccc|c} 1 & 2 & 1 & 4 \\ 0 & 1 & -1 & 1 \\ 1 & 3 & 0 & 0 \end{array} \right) \xrightarrow{\text{III}-\text{I}} \left(\begin{array}{ccc|c} 1 & 2 & 1 & 4 \\ 0 & 1 & -1 & 1 \\ 0 & 1 & -1 & 4 \end{array} \right) \xrightarrow{\text{III}+\text{II}} \left(\begin{array}{ccc|c} 1 & 2 & 1 & 4 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 3 \end{array} \right)$$

↳ System is not consistent

↳ There is no x_1, x_2, x_3 such that all equations are true

↳ There is no point common to all 3 planes.

~~Other cases of equations~~

- Choose h, k such that
- the system has no solution
 - — — has a unique solution
 - — — has many solutions

$$\begin{aligned} x_1 + h x_2 &= 2 \\ 4x_1 + 8x_2 &= k \end{aligned} \rightarrow \left(\begin{array}{cc|c} 1 & h & 2 \\ 4 & 8 & k \end{array} \right) \xrightarrow{\text{II}-4\cdot\text{I}} \left(\begin{array}{cc|c} 1 & h & 2 \\ 0 & 8-4h & k-8 \end{array} \right) \xrightarrow[8-4h \neq 0]{}$$

a) no solution \Rightarrow System is inconsistent \Rightarrow rightmost column is a pivot column
↳ $h=2, k \neq 8$.

b) unique solution \Rightarrow System is consistent

2nd column must be pivot column $\Rightarrow h \neq 2$

$$x_2 = \frac{k-8}{8-4h}$$

$$x_1 = 2 - h \cdot x_2$$

$$x_1 = 2 - h \cdot \frac{k-8}{8-4h}$$

c) many solutions \Rightarrow we must have one free variable

$$\Rightarrow 8-4h = k-8$$

$$k+4h=16$$

e.g. $k=4$
 $h=2$

a 3×3 matrix \underline{A} with non-zero entries such that $\underline{b} \notin \text{Span } \underline{A}$
 \underline{A} is in the Span of the columns of \underline{A} .

Solution: $\underline{A} = \begin{pmatrix} 1 & 2 & 1 \\ 1 & 2 & 3 \\ 1 & 2 & 3 \end{pmatrix} \quad \underline{b} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$

Why? Columns of \underline{A} are linearly dependent!

$$\text{Span } (\underline{a}_1, \underline{a}_2, \underline{a}_3) = C \cdot \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

$$\text{There is no } c \text{ such that } C \cdot \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

Give a geometric description of $\text{Span } \{\underline{v}_1, \underline{v}_2\}$ for $\underline{v}_1 = \begin{pmatrix} 3 \\ 0 \\ 2 \end{pmatrix}, \underline{v}_2 = \begin{pmatrix} -2 \\ 0 \\ 3 \end{pmatrix}$.

Solution: For every \underline{w} in $\text{Span } \{\underline{v}_1, \underline{v}_2\}$

$$\hookrightarrow \underline{w} = c_1 \begin{pmatrix} 3 \\ 0 \\ 2 \end{pmatrix} + c_2 \begin{pmatrix} -2 \\ 0 \\ 3 \end{pmatrix} = \begin{pmatrix} 3c_1 - 2c_2 \\ 0 \\ 2c_1 + 3c_2 \end{pmatrix}$$

\hookrightarrow Real part is always zero

$\hookrightarrow \text{span } \{\underline{v}_1, \underline{v}_2\} \subset \text{the } x-z\text{-plane}$

Let \underline{A} be an $m \times n$ matrix and let $\underline{u}, \underline{v}$ be vectors in \mathbb{R}^n with the property $\underline{A}\underline{u} = \underline{0}, \underline{A}\underline{v} = \underline{0}$. Show that $\underline{A}(c\underline{u} + d\underline{v}) = \underline{0}$ for every scalar constants c, d .

Proof:

$$\begin{aligned} \underline{A}(c\underline{u} + d\underline{v}) &= \underline{A}(c\underline{u}) + \underline{A}(d\underline{v}) = c \cdot \underline{A}\underline{u} + d \cdot \underline{A}\underline{v} \\ &= c \cdot \underline{0} + d \cdot \underline{0} = \underline{0} \quad \checkmark \end{aligned}$$

Are the vectors: $\begin{pmatrix} 5 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ 3 \end{pmatrix}, \begin{pmatrix} 4 \\ 8 \end{pmatrix}, \begin{pmatrix} 6 \\ 7 \end{pmatrix}$ linearly independent?

Find value(s) of h such that the following three vectors are linearly independent:

$$\begin{pmatrix} 1 \\ -1 \\ 4 \end{pmatrix}, \begin{pmatrix} 2 \\ -5 \\ 7 \end{pmatrix}, \begin{pmatrix} -1 \\ 5 \\ h \end{pmatrix}$$

Solve the system:

$$\begin{pmatrix} 1 & 2 & -1 \\ -1 & -5 & 5 \\ 4 & 7 & h \end{pmatrix} \xrightarrow{\text{I+II}} \begin{pmatrix} 1 & 3 & -1 \\ 0 & -2 & 4 \\ 0 & -5 & h+4 \end{pmatrix} \xrightarrow{\text{III}-4 \cdot \text{I}} \begin{pmatrix} 1 & 3 & -1 \\ 0 & 1 & -2 \\ 0 & 1 & \frac{h+4}{-5} \end{pmatrix}$$

For linear dependence we must have free variables

$$\begin{cases} \frac{h+4}{-5} = -2 \\ h+4 = 10 \\ h = 6 \end{cases}$$